

Econometrics for Climate Change

Session 1 — Probability, Statistics & Linear Regression

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Course Overview

Who am I?

- John Gomez
- Environmental and Public economics
- Applied Econometrics
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What I will be doing in the course?

- Empirical/statistical modeling
- "Intro to econometrics for Climate Change"
- Four sessions
- Assist in the projects: Uncertainty that need from statistical methods to be answer or resolved

Sessions Overview:

- ① Basics of econometrics
- ② Basics of econometrics (cont.) + Estimation of Damage functions
- ③ Causal Inference in Statistics and Econometrics
- ④ Causal Inferences for Climate Change Economic Dynamics

What to do for succeed?

- ① Short time + too many new concepts
- ② Not time for the details -> enough time to make connections
- ③ How is this useful to discuss the consequences of Climate Change

Session 1: Basics of Econometrics

Objectives for this session

- Review core probability concepts
- Understand sampling and statistical inference
- Introduce the linear regression model
- Interpret OLS in climate-related applications

Question 1

Question

What is the main difference between probability and statistics?

- A. Probability estimates parameters from data; statistics studies axioms.
- B. Probability studies random outcomes given a model; statistics infers unknowns from data.
- C. Probability is only for discrete variables; statistics for continuous variables.
- D. They are equivalent terms.

Why Econometrics?

Probability, Statistics, and Econometrics

Concept: Probability

Probability is the mathematical theory that models uncertainty.

- Probability space:
 - Ω : Sample space,
 - $\mathcal{F}$: Sigma algebra,
 - P : Probability measures
- Random variables
- Probability Distributions
- Moment functions
- Conditional expectations

Why Econometrics?

Probability, Statistics, and Econometrics

Concept: Probability

Probability is the mathematical theory that models uncertainty.

Concept: Statistics

Statistics is the discipline that uses probability theory to learn about unknown population quantities from observed data.

- Estimation
- Sampling distribution
- Hypothesis testing
- Model fitting

Why Econometrics?

Probability, Statistics, and Econometrics

Concept: Probability

Probability is the mathematical theory that models uncertainty.

Concept: Statistics

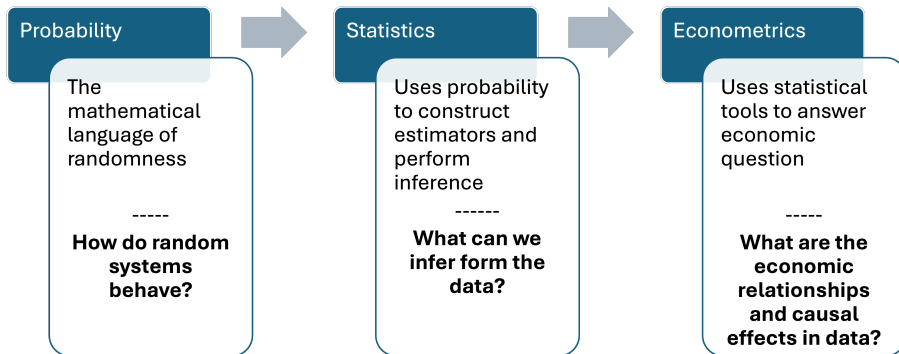
Statistics is the discipline that uses probability theory to learn about unknown population quantities from observed data.

Concept: Econometrics

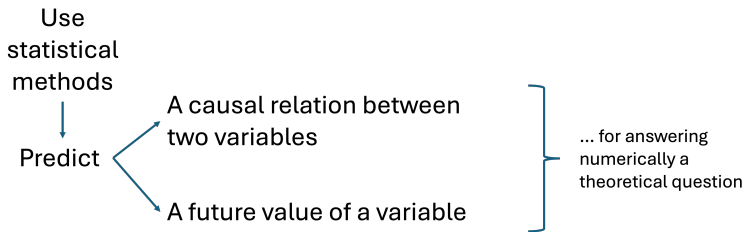
Econometrics is the application of statistical methods to economic data in order to

- 1 Estimate economic relationships
- 2 Test economic theories

Why Econometrics?



Why Econometrics? Random Variables



- Example in **Climate economics**:
 - Estimating impact of temperature on productivity
 - Measuring effect of carbon pricing
 - Quantifying emissions–growth relationship
- Superficially, seems a matter of which **Random Variables** we are looking to

Question 2

Question

Suppose we model next year's average temperature anomaly in a country as uncertain. Which of the following best represents a *random variable* in this context?

- A. The actual temperature anomaly that will be observed next year.
- B. The historical average temperature anomaly from 1980–2020.
- C. A function that assigns a numerical temperature anomaly to each possible future state of the world.
- D. A dataset containing temperature observations from multiple countries.

Random variables

An example:

$\Omega: \{\text{Very hot, Very cold}\}$

$P(\text{Very hot}) = p, P(\text{Very cold}) = 1 - p$

RVs have a Value and Index structure.

A random variable will be the function:

$$T : \Omega \rightarrow \mathbb{R}$$

that assigns numerical variables to each state

$$T(\text{Very hot}) = 35$$

$$T(\text{Very cold}) = 5$$

Question 3

Question

What are the differences between the following random variables?

- ① Number of floods across countries
- ② CO_2 per capita across countries
- ③ Number of storms per year
- ④ Temperature anomaly over time
- ⑤ Emissions

RV - Index structure

How the variables are indexed? - Type of data

- ① Time series
- ② Cross sectional
- ③ Longitudinal or panel data
- ④ Pool

	Time 						
Unit		1	2	...	t	...	T
	1	X_1	X_2		X_t		X_T

RV - Index structure

How the variables are indexed? - Type of data

- ① Time series
- ② Cross sectional
- ③ Longitudinal or panel data
- ④ Pool

	Time	
		1
Unit 	1	X_1
	2	X_2
	...	
	i	X_i
	...	
	n	X_n

RV - Index structure

How the variables are indexed? - Type of data

- ① Time series
- ② Cross sectional
- ③ Longitudinal or panel data
- ④ Pool

		Time 					
Unit 		1	2	...	t	...	T
	1	X_{11}	X_{12}		X_{t1}		X_{T1}
	2	X_{21}	X_{22}		X_{t2}		X_{T2}
	...	...	...		...		
	i	X_{i1}	X_{i2}	...	X_{ti}	...	X_{Ti}
	...	...	...		...		...
	n	X_{n1}	X_{n2}	...	X_{tn}	...	X_{Tn}

RV - Index structure

How the variables are indexed? - Type of data

- ① Time series
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Unit	Time 					
	1	...	T1	T1+1	...	T2
1	X_{11}	...	$X_{T_1 1}$			
...	X_{12}	...	$X_{T_1 2}$			
n_1	X_{1n_1}	...	$X_{T_1 n_1}$			
n_{1+1}				$X_{(T_1+1)(n_1+1)}$	...	$X_{(T_2)(n_1+1)}$
...				...		...
n_2				$X_{(T_1+1)n_2}$	...	$X_{T_2 n_2}$

RV - Index structure

How the variables are indexed? - Type of data

- ① Time series
- ② Cross sectional
- ③ Longitudinal or panel data
- ④ Pool

Always identified your **unit of observation!**

RV - Value structure

Two type of values structure:

Concept: Discrete RVs

The set of values it can take (that is the **support**) is finite or countably infinite.

Examples?

Concept: Continuous RVs

It takes values in an uncountable set, typically an interval of $\mathbb{R}$.

Examples?

RV - Probability functions

Concept: Probability Function

A probability function assigns/indicates probabilities to events in a probability space $\mathcal{F}$

$$f(X = x) : \mathcal{F} \rightarrow [0, 1] \quad (1)$$

- ① Non-negativity - Non negative probabilities
- ② Normalization - Sum to one
- ③ Countable additivity - The probability of disjoint events is the sum of the events' probabilities

Discrete RVs

Continuous RVs

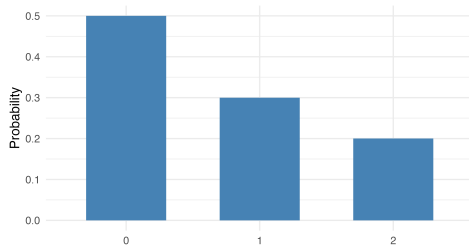
RV - Probability functions

Concept: Probability Function

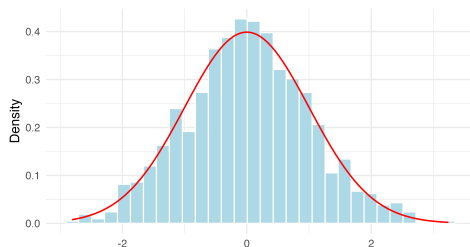
A probability function assigns/indicates probabilities to events in a probability space $\mathcal{F}$

$$f(X = x) : \mathcal{F} \rightarrow [0, 1] \quad (1)$$

Discrete RVs
Probability mass function



Continuous RVs
Probability density function

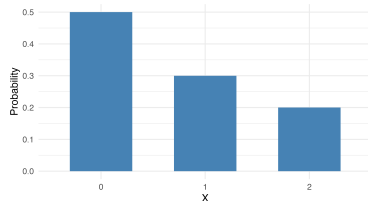


RV - Expected value

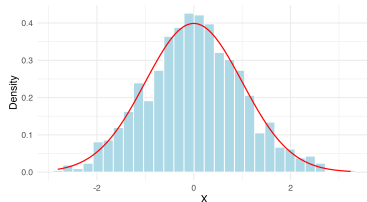
Concept: Expected value

The expected value (or **mean**) of X , denoted $E[X]$, is the probability-weighted average of its possible values.

Discrete RVs



Continuous RVs

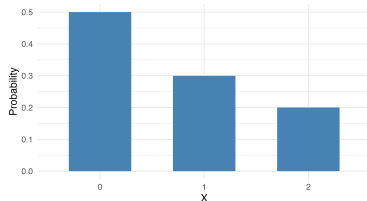


RV - Expected value

Concept: Expected value

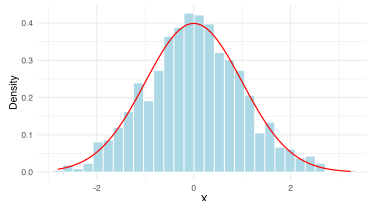
The expected value (or **mean**) of X , denoted $E[X]$, is the probability-weighted average of its possible values.

Discrete RVs



$$E[X] = \sum_x x f(x)$$

Continuous RVs



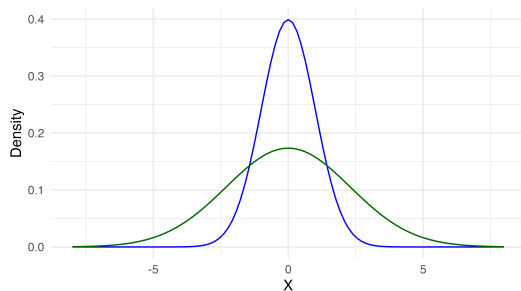
$$E[X] = \int_{-\infty}^{\infty} x f(x) dx$$

RV - Variance

Concept: Variance

The variance of a random variable X , denoted $\text{Var}(X)$, measures the expected squared deviation of X from its mean.

$$\text{Var}(X) = E[(X - E[X])^2] \quad (2)$$



Where does Statistics enter?

- Let us suppose we have a RV X of interest (e.g., GDP, Emissions)
- We would like to gather information about the dsitribution of this variable, lets say the mean ($E[X]$ or μ_X)
- μ_X is the value for the whole the population
- We do not have access to that!!

The best I can do is to get a **Random Sample** (S)

Concept: Random Sample

A **random sample** of RV X is a series of n realizations of X ($x_1, x_2, \dots$) that satisfy a series of conditions:

- ① Each x_i is the result of randomly select a value for X , **independently** of the other possible values (x_j)
- ② Each realization will follow the distribution of X

That is, we will work with **Independently and indetically distributed**, or **iid**, samples.

Statistic and Inference - Estimator

Based on the sample, we will build estimators

Concept: Estimator

Any function of the Sample ($Estimator(x) : S \rightarrow \mathbb{R}$, build with the purpose to learn something about the distribution of a given RV.

- We want those estimators to have a series of properties:
 - **Unbias:** $E[Estimator] = Parameter$
 - **Efficiency:** $EstA$ is more efficient than $EstB$ if it has lower variance
 - **Consistency:** $\bar{X} \rightarrow^p Parameter$
 - A known distribution
- Other properties are convenient, but not fully required:
 - **Linear:** $\bar{X}$ is a linear function of the elements in S

Question 5

Let us assume we want to estimate the expected value of the random variable X , for which we have an iid sample S of size n . We have three possible candidates and we want to evaluate their properties:

	Is it linear?	Unbiased?	Efficient?
$\tilde{X} = x_2 + x_3$			
$\hat{X} = x_1$			
$\bar{X} = \frac{\sum_{i=1}^n x_i}{n}$			

Question 4

Question

What does it mean for an estimator to be **BLUE**?

- A. Best Unbiased Linear Estimator
- B. Biased Linear Uniform Estimator
- C. Bayesian Linear Unrestricted Estimator
- D. Best Linear Unbiased Estimator

Cool property of the sample average

- We already see that the $\bar{X}$ is unbiased and linear
- It can be shown, but it is also the most efficient within all linear estimators
- The **Law of large Numbers** will guarantee it is **consistent**
- The **Central Limit Theorem** tell us that

$$\frac{\bar{X} - \mu_x}{\sigma^2/n} \sim N(0, 1)$$

How we will use this for Inference?

Linear regression - Relation between two variables

Law of Iterated Expectations

$$E[Y] = E[E[Y|X]]$$

We observe a random sample:

$$\{(Y_i, X_i)\}_{i=1}^n$$

Climate example: Expected agricultural output given temperature

From Conditional Expectation to Regression

Define:

$$m(X) = E[Y|X]$$

Linear approximation:

$$m(X) \approx \beta_0 + \beta_1 X$$

Regression = Best Linear Predictor

Linear Regression Model

$$Y_i = \beta_0 + \beta_1 X_i + u_i$$

Where:

- Y_i : outcome (e.g., emissions per capita)
- X_i : regressor (e.g., GDP per capita)
- u_i : unobserved factors

OLS estimator derivation